

Uva Wellassa University, Sri Lanka
End Semester Examination – March/April 2013
SCT 462-2 Control Theory

Time: Two (02) Hours

Total 04 Questions
Answer all questions



1.

- I. Give three examples of **open loop** systems. (03 marks)
- II. Draw a block diagram of a **feedback control system** and name the components. (05 marks)
- III. What is the voltage gain of the following arrangement?

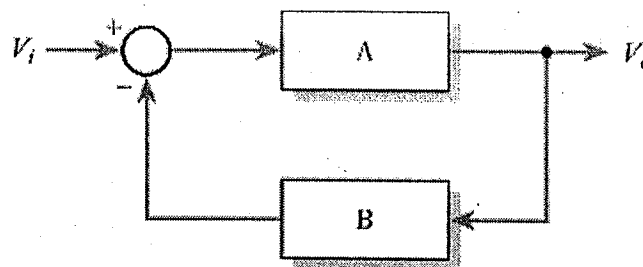


Fig. Q1-1

(05 marks)

- IV. Obtain mathematical model of the mechanical system shown in Fig. Q1-2, where $m = 1$ kg, $b = 3$ N-sec/m, and $k = 2$ N/m. Assume zero initial conditions.

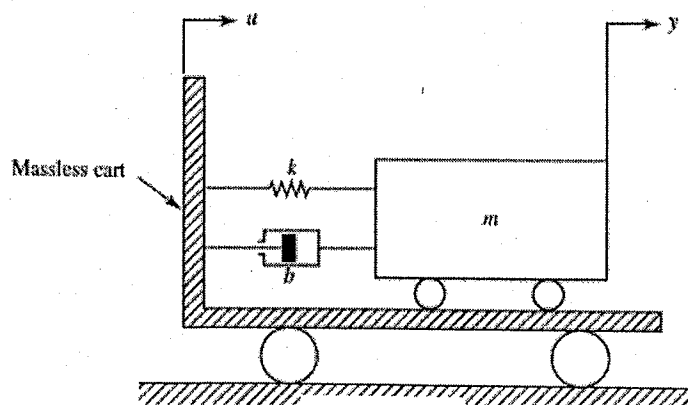


Fig. Q1-2

- Obtain the mathematical equation for the motion of the mass. (Assume no external forcing function.)
- Obtain the Laplace transform of the system.
- Obtain time domain response for the above system and plot.

(12 marks)

2.

- Consider the unit-step response of a unity-feedback control system whose open-loop transfer function is

$$G(s) = \frac{2}{(5s+10)}$$

Obtain the unit-impulse response and unit ramp response.

(10 marks)

- Fig. Q2-1 shows a system with two inputs and two outputs.

- Derive $C_1(s)/R_1(s)$, $C_1(s)/R_2(s)$, $C_2(s)/R_1(s)$, and $C_2(s)/R_2(s)$. (In deriving outputs for $R_1(s)$, assume that $R_2(s)$ is zero, and vice versa.)
- Use the above results to draw a simplified block diagram for $C_1(s)/R_1(s)$, $C_1(s)/R_2(s)$.

(15 marks)

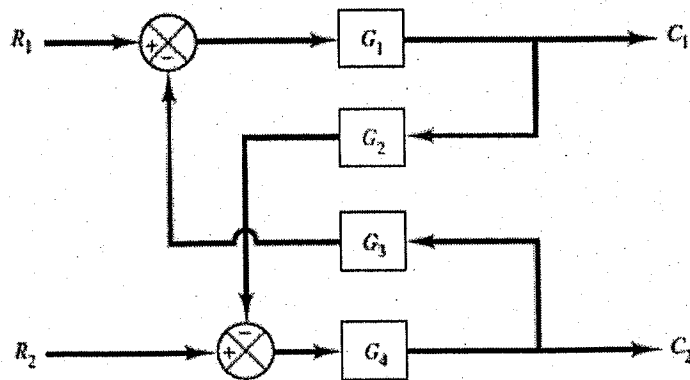


Fig. Q2-1

3.

- I. How a second order system is classified depending on the value of damping?
Draw a suitable graph to show the transient behavior of a second order system.
(05 marks)

- II. Consider the system shown in Fig.Q3-1. Determine the following.

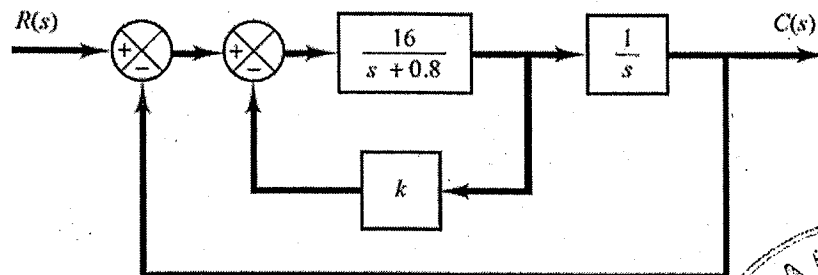


Fig. Q3-1

- Value of k such that the damping ratio ξ is 0.5.
- Rise time t_r
- Peak time t_p
- Maximum overshoot M_p
- Settling time t_s for a unit-step response.



(10 marks)

- III. The closed loop transfer function of second order system is

$$\frac{C(s)}{R(s)} = \frac{10}{(s^2 + 6s + 10)}$$

Determine the damping ratio and the natural frequency of oscillations.

(10 marks)

4.

- I. Consider the system shown in Q4-1. For the sinusoidal input $x(t) = X \sin(\omega t)$ obtain the steady state output y_{ss} in standard notation.

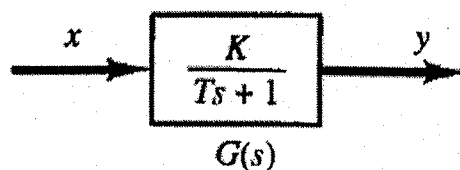


Fig. Q4-1

(04 marks)

- II. Consider the following characteristic equation: Using the Routh stability criterion, determine the range of K for stability.

$$s^4 + 2s^3 + (4 + K)s^2 + 9s + 25 = 0$$

(06 marks)

- III. Consider the system shown in Fig. Q4-2. Determine the following.

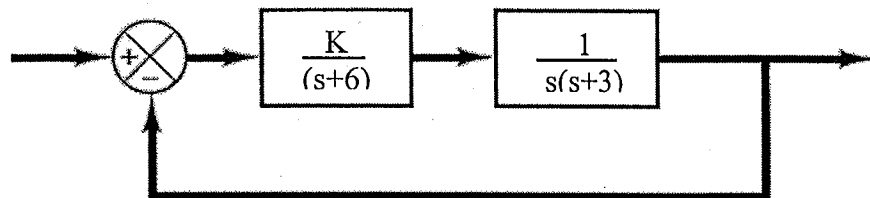


Fig. Q4-2

- Root loci on the real axis
- The asymptotes of the root loci.
- The breakaway point.
- The points where root loci crosses imaginary axis.
- Draw the root loci, based on the information you obtained for above questions.
- Value of K for marginal stability.

(15 marks)